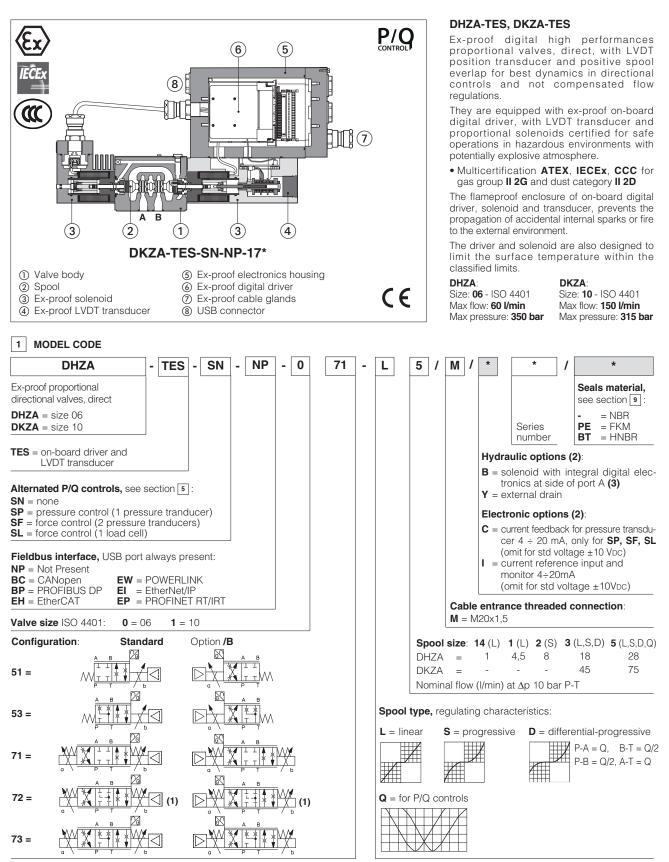
# atos 🛆

# Ex-proof digital proportional directional valves high performance

direct, with on-board driver, LVDT transducer and positive spool overlap - ATEX, IECEx, CCC



(1) Only for DKZA-\*-S5 the spool overlapping type 2 provides the same characteristic of type 1, but in central position the internal leakages from P to A and B are drained to tank, avoiding the drift of cylinders with differential areas
 (2) For possible combined options, see section 15
 (3) In standard configuration the solenoid with on-board digital driver and position transducer are at side port B

# 2 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FX900** and in the user manuals included in the E-SW-\* programming software.

### **3 VALVE SETTINGS AND PROGRAMMING TOOLS**

WARNING: the below operation must be performed in a safety area

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver (see table **FX900**). For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options (see table GS500):E-SW-BASICsupport: NP (USB)PS (Serial)IR (Infrared)

E-SW-FIELDBUS	support:	BC (CANopen)	BP (PROFIBUS DP)	EH (EtherCAT)
		EW (POWERLINK)	EI (EtherNet/IP)	EP (PROFINET)
E-SW-*/PQ	support:	valves with SP, SF, S	SL alternated control (e	e.g. E-SW-BASIC/PQ)

 $\Delta$  WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection

igvee WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

# 4 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

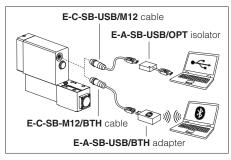
#### 5 ALTERNATED P/Q CONTROLS - see tech. table FX500

**S**<sup>\*</sup> options add the closed loop control of pressure (**SP**) or force (**SF** and **SL**) to the basic functions of proportional directional valves flow regulation. A dedicated algorithm alternates pressure (force) depending on the actual hydraulic system conditions. An additional connector is available for transducers to be interfaced to the valve's driver (1 pressure transducer for SP, 2 pressure transducers for SF or 1 load cell for SL). The alternated pressure control (SP) is possible only for specific installation conditions.

#### 6 GENERAL CHARACTERISTICS

Assembly position	Any position				
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100				
MTTFd valves according to EN ISO 13849	150 years, see technical table P007				
Ambient temperature range	<b>Standard</b> = $-20^{\circ}C \div +60^{\circ}C$	<b>/PE</b> option = $-20^{\circ}C \div +60^{\circ}C$	<b>/BT</b> option = $-40^{\circ}C \div +60^{\circ}C$		
Storage temperature range	<b>Standard</b> = $-20^{\circ}C \div +70^{\circ}C$	<b>/PE</b> option = $-20^{\circ}C \div +70^{\circ}C$	<b>/BT</b> option = $-40^{\circ}C \div +70^{\circ}C$		
Surface protection Zinc coating with black passivation					
Corrosion resistance	Salt spray test (EN ISO 9227) > 200 h				
Explosion proof protection, see section 11         -Flame proof enclosure "Ex d"         Compliance       -Dust ignition protection by enclosure "Ex t"					
	RoHs Directive 2011/65/EU as last update by 2015/863/EU REACH Regulation (EC) n°1907/2006				

#### USB or Bluetooth connection



# 7 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model					DHZA			DKZA	
Pressure limits	[bar]	ports <b>P</b> , <b>A</b> , <b>B</b> = 350; <b>T</b> = 210 (250 with external drain /Y) <b>Y</b> = 10					with external draw	'	
Configuration				51,	53, 71, 73		51, 53,	71, 73	72
Spool Type		L14	L1	S2	L3, S3, D3	L5, S5, D5, Q5	L3, S3, D3	L5, S5, D5, Q5	S5
Nominal flow									
[l/min]	at ∆p= 10 bar	1	4,5	8	18	28	45	75	75
∆р Р-Т	at ∆p= 30 bar	1,7	8	14	30	50	80	130	130
	max permissible flow	2,6	12	21	40	60	90	150	150
∆p max P-T	[bar]	70	70	70	50	50	40	40	40
Leakage [cm <sup>3</sup> /r	nin]	<	30 (at p =	= 100 ba	ar); <135 (at p = 3	50 bar)	<80 (at p = 10	00 bar); <600 (	at p = 315 bar)
Response time	(1) [ms]				≤ 20			≤ 25	
Hysteresis		≤ 0,2 [% of max regulation]							
Repeatibility		± 0,1 [% of max regulation]							
Thermal drift					zero point disp	lacement < 1% a	at $\Delta T = 40^{\circ}C$		

(1) (0-100% step signal)

# 8 ELECTRICAL CHARACTERISTICS

Power supplies	Nominal         : +24 VDC           Rectified and filtered         : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)						
Max power consumption	35 W						
Analog input signals		Voltage: range $\pm 10 \text{ VDC}$ (24 VMAX tollerant)Input impedance: Ri > 50 k $\Omega$ Current: range $\pm 20 \text{ mA}$ Input impedance: Ri = 500 $\Omega$					
Insulation class		H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account					
Monitor outputs		Output range:         voltage         ±10 VDc @ max 5 mA           current         ±20 mA @ max 500 Ω load resistance					
Enable input	Range: 0 ÷ 5 VDC (OFF	Range: $0 \div 5$ VDC (OFF state), $9 \div 24$ VDC (ON state), $5 \div 9$ VDC (not accepted); Input impedance: Ri > 10 k $\Omega$					
Fault output	Output range: 0 ÷ 24 VDC (ON state > [power supply - 2 V]; OFF state < 1 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)						
Pressure/force transducer power supply (only for SP, SF, SL)	+24VDC @ max 100 mA (E-ATRA-7 see tech table GX800)						
Alarms		Solenoid not connected/short circuit, cable break with current reference signal, over/under temperature, valve spool transducer malfunctions					
Protection degree to DIN EN60529	IP66/67 with relevant of	cable gland					
Duty factor	Continuous rating (ED=100%)						
Tropicalization	Tropical coating on ele	ectronics PCB					
Additional characteristics	Short circuit protection of solenoid current supply; spool position control (SN) or pressure/force control (SP, SF, SL) by P.I.D. with rapid solenoid switching; protection against reverse polarity of power supply						
Electromagnetic compatibility (EMC)							
Communication interface	USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT, POWERLINK, EtherNet/IP, PROFINET IO RT / IRT EC 61158			
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX			

Note: a maximum time of 800 ms (depending on communication type) have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

9 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$ , with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$ , with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$			
Recommended viscosity		20 ÷ 100 mm²/s - max allowed range 15 ÷ 380 mm²/s			
Max fluid normal operation		ISO4406 class 18/16/13 NAS1	see also filter section at		
contamination level	longer life	ISO4406 class 16/14/11 NAS1	www.atos.com or KTF catalog		
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard	
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524	
Flame resistant without wa	ter	FKM	HFDU, HFDR ISO 129		
Flame resistant with water	(1)	NBR, HNBR	HFC	100 12922	

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

# (1) Performance limitations in case of flame resistant fluids with water:

-max operating pressure = 210 bar -max fluid temperature = 50°C

# 10 CERTIFICATION DATA

Valve type	DHZA, DKZA					
Certifications	Multicertification Group II ATEX IECEX CCC					
Solenoid		Single solenoid		Double solenoid		
Solenoid certified code		OZA-TES			S, OZA-A	
Type examination certificate (1)	ATEX: TUV IT	18 ATEX 068 X		• ATEX: TUV IT 18 ATE	X 068 X	
	IECEx: IECEx	TPS 19.0004X		• IECEX: IECEX TPS 19.	0004X	
	• CCC: 202132	2307004057		• CCC: 2021322307004	1057	
				• ATEX: CESI 02 ATEX	014	
					.0010x	
				• CCC: 2020322307003240		
Method of protection	Ex II 2D Ex tb • IECEx Ex db IIC T6/ Ex tb IIIC T85 • CCC Ex d IIC T6/T5	D IIC T6/T5/T4 Gb IIIC T85°C/T100° T5/T4 Gb °C/T100°C/T135°	°C/T135°C Db C Db	<ul> <li>ATEX, EAC Ex II 2G Ex d IIC T4/T3 Ex II 2D Ex tb IIIC T13</li> <li>IECEx Ex d IIC T4/T3 Gb Ex tb IIIC T135°C/T20</li> <li>CCC Ex d IIC T4/T3 Gb Ex tD A21 IP66/IP67 T</li> </ul>	5°C/T200°C Db 0°C Db	
Temperature class	Т6	Т5	T4	T4	Т3	
Surface temperature	≤ 85 °C	≤ 100 °C	≤ 135 °C	≤ 135 °C	≤ 200 °C	
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +55 °C	-40 ÷ +70 °C	-40 ÷ +40 °C	-40 ÷ +70 °C	
Applicable Standards	EN 60079-0         EN 60079-1         EN 60079-31           IEC 60079-0         IEC 60079-31         IEC 60079-1					
Cable entrance: threaded connection			$\mathbf{M} = \mathbf{M}$	20x1,5		

(1) The type examinator certificates can be downloaded from www.atos.com

(2) The driver and solenoids are certified for minimum ambient temperature -40°C.

In case the complete valve must withstand with minimum ambient temperature -40°C, select /BT in the model code.

# / WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification.

11 CABLE SPECIFICATION AND TEMPERATURE - Power supply and grounding cables have to comply with following characteristics:

Power supply and signals: section of wire = 1,0 mm <sup>2</sup>	Grounding: section of external ground wire = 4 mm <sup>2</sup>

#### 11.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]
40 °C	T6	85 °C	0° 08
55 °C	T5	100 °C	90 °C
70 °C	Τ4	135 °C	110 °C

#### 12 CABLE GLANDS

Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table **KX800 Note:** a Loctite sealant type 545, should be used on the cable gland entry threads

#### 13 HYDRAULIC OPTIONS

B = Solenoid, integral electronics and position transducer at side of port A of the main stage. For hydraulic configuration vs reference signal, see 17.1

Y = Option /Y is mandatory if the pressure in port T exceeds 210 bar

#### 14 ELECTRONIC OPTIONS

I = It provides 4 ÷ 20 mA current reference signal, instead of the standard ±10 VDC.

Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

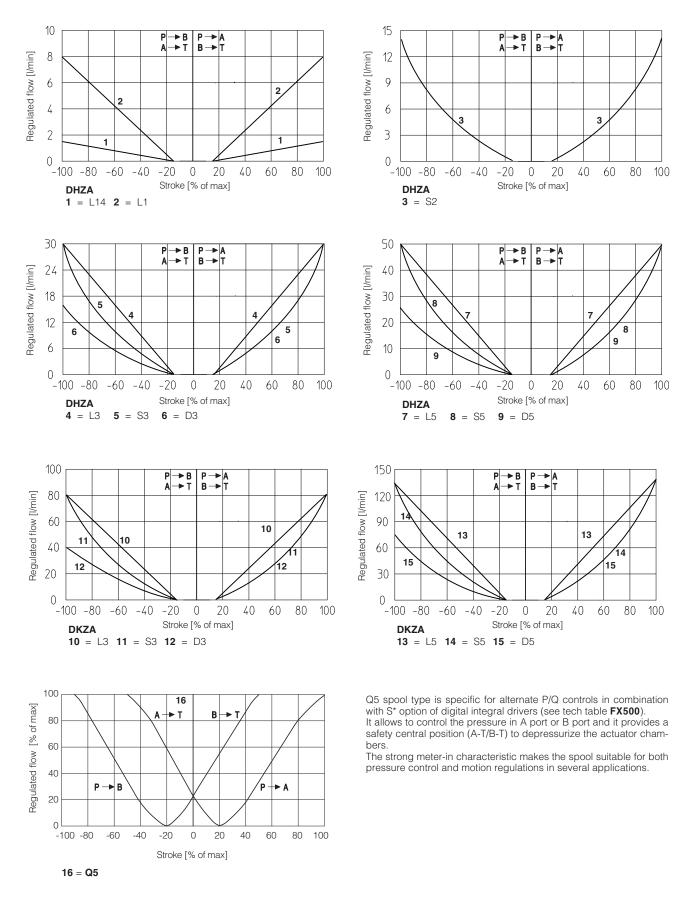
#### C = Only for SP, SF, SL

Option /C is available to connect pressure (force) transducers with 4 ÷ 20 mA current output signal, instead of the standard ±10 VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA.

# 15 POSSIBLE COMBINED OPTIONS

For SN: /BI, /BY, /IY For SP, SF, SL: /BI, /BY, /IY, /CI, /BCI, CIY, BCIY

16.1 Regulation diagrams - values measure at  $\Delta p$  30 bar P-T



#### Note:

Hydraulic configuration vs. reference signal for configurations 71 and 73 (standard and option /B) Reference signal  $\begin{array}{c} 0 & \div +10 \text{ V} \\ 12 & \div 20 \text{ mA} \end{array}$   $P \rightarrow A / B \rightarrow T$  Reference signal  $\begin{array}{c} 0 & \div -10 \text{ V} \\ 12 & \div 4 \text{ mA} \end{array}$   $P \rightarrow B / A \rightarrow T$ 

#### 17 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, ISO 4413).

#### 17.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000  $\mu$ F/40 V capacitance to single phase rectifiers or a 4700  $\mu$ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

#### 17.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000  $\mu$ F/40 V capacitance to single phase rectifiers or a 4700  $\mu$ F/40 V capacitance to three phase rectifiers. The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the dia-

The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

#### 17.3 Flow reference input signal (Q\_INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal.

Reference input signal is factory preset according to selected valve code, defaults are  $\pm 10$  VDC for standard and  $4 \div 20$  mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of  $\pm 10$  VDC or  $\pm 20$  mA. Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range  $0 \div 24$ VDC.

#### 17.4 Pressure or force reference input signal (F\_INPUT+) - only SP, SF, SL

Functionality of F\_INPUT+ signal (pin 12), is used as reference for the driver pressure/force closed loop (see tech. table FX500). Reference input signal is factory preset according to selected valve code, defaults are  $\pm 10$  VDC for standard and  $4 \div 20$  mA for /I option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of  $\pm 10$  VDC or  $\pm 20$  mA. Drivers with fieldbus interface can be software set to receive reference signal directly by the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range 0  $\div 24$ VDC.

#### 17.5 Flow monitor output signal (Q\_MONITOR)

The driver generates an analog output signal proportional to the actual spool position of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference, pilot spool position). Monitor output signal is factory preset according to selected valve code, defaults are  $\pm 10$  VDc for standard and  $4 \div 20$  mA for /l option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of  $\pm 10$  VDc or  $\pm 20$  mA.

#### 17.6 Pressure or force monitor output signal (F\_MONITOR) - only for SP, SF, SL

The driver generates an analog output signal proportional to alternated pressure/force control; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, force reference).

Monitor output signal is factory preset according to selected valve code, defaults are ±10 VDc for standard and 4 ÷ 20 mA for /l option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDc or ± 20 mA.

#### 17.7 Enable input signal (ENABLE)

To enable the driver, supply a 24 VDC on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

#### 17.8 Fault output signal (FAULT)

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

#### 17.9 Remote pressure/force transducer input signal - only for SP, SF, SL

Analog remote pressure transducers or load cell can be directly connected to the driver.

Analog input signal is factory preset according to selected valve code, defaults are  $\pm 10$  VDc for standard and  $4 \div 20$  mA for /C option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of  $\pm 10$  VDc or  $\pm 20$  mA. Refer to pressure/force transducer characteristics to select the transducer type according to specific application requirements (see table FX500).

#### 18 TERMINAL BOARD OVERVIEW

(1)       TR1       34       33       TR2       (3)         NC       7       32       31       EARTH         NC       7       30       29       NC         NC       7       30       29       NC         NC       7       82       27       NC       NC         NC       NC       10       10       10       10       10         NC       NC       26       25       NC       NC       BC (2)       BP (2)       EH, EW, Ei, EP         RX+       LINE_A       not used       NC       7       NC       NC       AX-         TX+       DGND       CAN_H       10       13       7       NC       CAN_GND       TX+         NC       SHIELD       CAN_L       11       13       F.MONITOR (1)       NC       NC         NPUT-       8       7       AGND       FAULT       VL       VL
--

(1) Connections available only SP, SF, SL

(2) For BC and BP executions the fieldbus connections have an internal pass-through connection

(3) Connection available only SF

# 19 ELECTRONIC CONNECTIONS

# 19.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	1	VO	Power supply 0 Vbc	Gnd - power supply
	2	V+	Power supply 24 VDc	Input - power supply
	3	VL0	Power supply 0 Vbc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 Vbc for driver's logic and communication	Input - power supply
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal
	6	ENABLE	Enable (24 Vbc) or disable (0 Vbc) the driver, referred to VL0	Input - on/off signal
	7	AGND	Analog ground	Gnd - analog signal
	8	INPUT-	Negative reference input signal for Q_INPUT+ and F_INPUT+	Input - analog signal
	9	Q_MONITOR	Flow monitor output signal: ±10 Vpc / ±20 mA maximum range, referred to AGND Defaults are: ±10 Vpc for standard and 4 ÷ 20 mA for /I option	Output - analog signal <b>Software selectable</b>
	10	Q_INPUT+	Flow reference input signal: $\pm 10$ Vpc / $\pm 20$ mA maximum range Defaults are: $\pm 10$ Vpc for standard and 4 $\div 20$ mA for /I option	Input - analog signal Software selectable
			Pressure/Force monitor output signal: $\pm 10 \text{ Vbc} / \pm 20 \text{ mA}$ maximum range, referred to AGND (1) Defaults are: $\pm 10 \text{ Vbc}$ for standard and $4 \div 20 \text{ mA}$ for /I option	Output - analog signal <b>Software selectable</b>
	12     F_INPUT+     Pressure/Force reference input signal: ±10 Vbc / ±20 mA maximum range (1)       12     Defaults are: ±10 Vbc for standard and 4 ÷ 20 mA for /I option		Input - analog signal Software selectable	
	31	EARTH	Internally connected to driver housing	

(1) Available only for SP, SF, SL

#### 19.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	Driver view	B
	1	+5V_USB	Power supply		
	2	ID	Identification	5	
B	3	GND_USB	Signal zero data line		
	4	D-	Data line -	4 - <u>3</u>	
	5	D+	Data line +	(female)	

CABLE ENTRANCE

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# 19.3 BC fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	CAN_L	Bus line (low)
	16	CAN_SHLD	Shield
C1	18	CAN_GND	Signal zero data line
	20	CAN_H	Bus line (high)
	22	not used	Pass-through connection (1)

(1) Pin 19 and 22 can be fed with external +5V supply of CAN interface

#### 19.4 BP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	
	14	SHIELD		
	16	+5V	Power supply	
C1	18	DGND	Data line and termination signal zero	
•••	20	LINE_B	Bus line (low)	
	22	LINE_A	Bus line (high)	

#### 19.5 EH, EW, EI, EP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	NC	do not connect
	16	тх-	Transmitter
C1	18	TX+	Transmitter
	20	RX-	Receiver
(input)	22	RX+	Receiver

	21 <b>CAN_H</b>		Bus line (high)				
CABLE							
ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS				
	13	SHIELD					
	15	+5V	Power supply				
C2	17	DGND	Data line and termination signal zero				
	10		B II (IIII)				

TECHNICAL SPECIFICATIONS

Bus line (low)

Bus line (high)

Bus line (low)

Signal zero data line

Pass-through connection (1)

Shield

SIGNAL

CAN\_L

CAN\_SHLD

CAN\_GND

not used

LINE\_A

LINE\_B

PIN

13

15

17

19

19

21

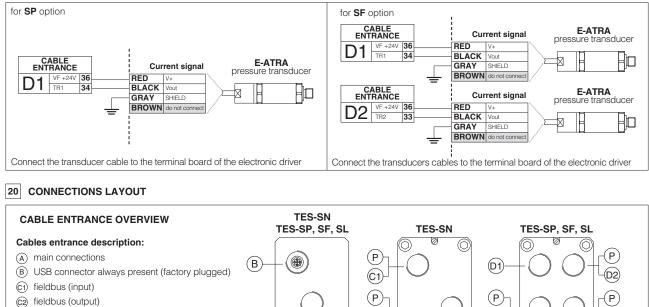
CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	TX-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver

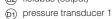
#### 19.6 Remote pressure transducer connector - only for SP, SF, SL

CABLE ENTRANCES	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES	SP, SL - Single transducer (1) Voltage   Current		SF - Double transducers (1 Voltage   Current				
	33	TR2	2nd signal transducer ±10 Vpc / ±20 mA maximum range	Input - analog signal <b>Software selectable</b>	/	/	Connect	Connect			
וט	34	TR1	1st ignal transducer ±10 Vpc / ±20 mA maximum range	Input - analog signal <b>Software selectable</b>	Connect	Connect	Connect	Connect			
ר2	35	AGND	Common gnd for transducer power and signals	Common gnd	Connect	/	Connect	/			
	36	VF +24V	Power supply +24VDC	Output - power supply	Connect	Connect	Connect	Connect			

FX1	30

#### E-ATRA remote pressure transducer connection - see tech table GX800



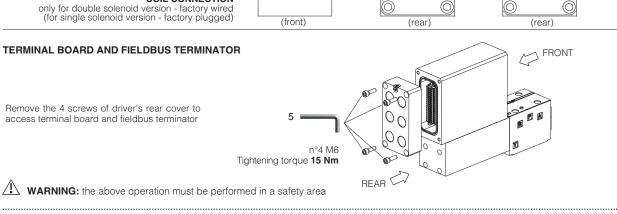


- (D2) pressure transducer 2

(P) threaded plug



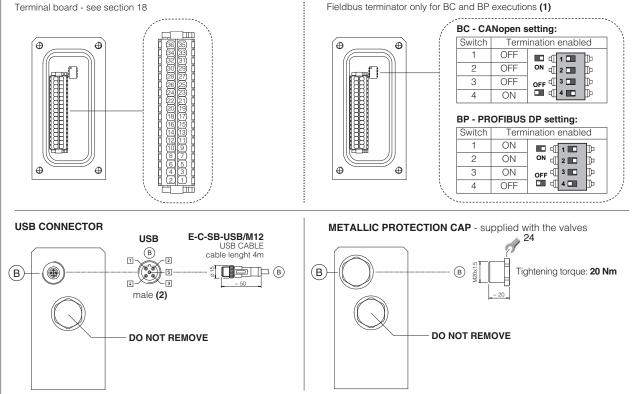




( A

( A )

P



(1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF (2) Pin layout always referred to driver's view

# 20.1 Cable glands and threaded plug for TES-SN - see tech table KX800 $\,$

	То	be ordere	ed separat	ely		
Communication interfaces		gland entrance		ed plug entrance	Cable entrance overview	Notes
NP	1	A	none	none		Cable entrance A is open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "via stub" connection	2	C1 A	1	C2		Cable entrance A, C1, C2 are open for costumers
BC, BP, EH, EW, EI, EP "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers

# 20.2 Cable glands and threaded plug for TES-SP, SL - see tech table KX800

Communication	То	be ordere	ed separat	ely	Cable entrance	
interfaces		gland entrance		ed plug entrance	overview	Notes
NP	2	D1 A	none	none		Cable entrance A, D1 are open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "via stub" connection	3	D1 C1 A	1	C2	00 00 00 00 00 00 00 00 00	Cable entrance A, C1, C2, D1 are open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "daisy chain" connection	4	D1 C1 - C2 A	none	none		Cable entrance A, C1, C2, D1 are open for costumers Cable entrance P are factory plugged

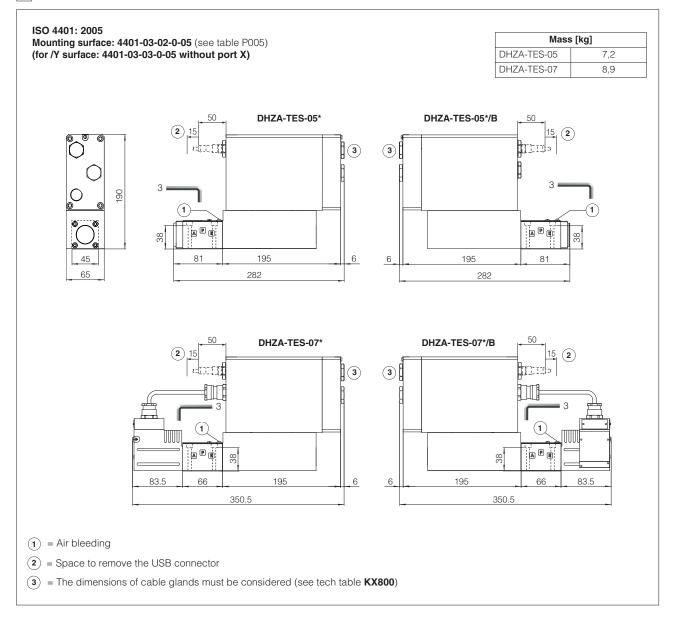
# 20.3 Cable glands and threaded plug for TES-SF - see tech table KX800 $\,$

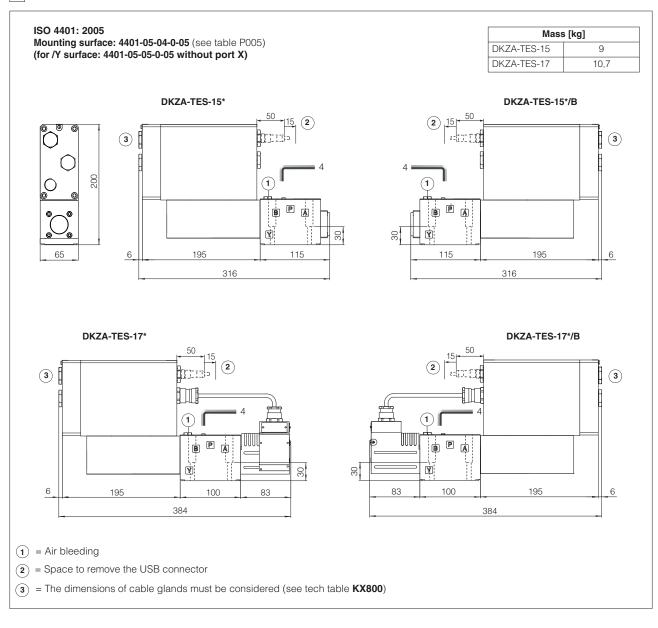
Communication			ed separat	-	Cable entrance		
interfaces		gland entrance	Thread quantity	ed plug entrance	overview	Notes	
NP	3	D1 D2 A	none	none	5) P P 99 A P	Cable entrance A, D1, D2 are open for costumers Cable entrance P are factory plugged	
BC, BP, EH, EW, EI, EP "via stub" connection	4	D1 - D2 C1 A	1	C2	000 000 000 000 000	Cable entrance A, C1, C2, D1, D2 are open for costumers Cable entrance P is factory plugged	
BC, BP, EH, EW, EI, EP "daisy chain" connection	5	D1 - D2 C1 - C2 A	none	none		Cable entrance A, C1, C2, D1, D2 are open for costumers Cable entrance P is factory plugged	

# 21 FASTENING BOLTS AND SEALS

	DHZA	DKZA
	<b>Fastening bolts:</b> 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm	<b>Fastening bolts:</b> 4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm
0	Seals: 4 OR 108; Diameter of ports A, B, P, T: Ø 7,5 mm (max) 1 OR 2025 Diameter of port Y: Ø = 3,2 mm (only for /Y option)	Seals: 5 OR 2050; Diameter of ports A, B, P, T: Ø 11,2 mm (max) 1 OR 108 Diameter of port Y: Ø = 5 mm (only for /Y option)

# 22 INSTALLATION DIMENSIONS FOR DHZA [mm]





# 24 RELATED DOCUMENTATION

X010	Basics for electrohydraulics in hazardous environments	GS500	Programming tools
X020	Summary of Atos ex-proof components certified to ATEX, IECEx, EAC,	GS510	Fieldbus
	CCC, PESO	KX800	Cable glands for ex-proof valves
FX900	Operating and manintenance norms for ex-proof proportional valves	P005	Mounting surfaces for electrohydraulic valves
FX500	Ex-proof for digital proportionals with P/Q control	E-MAN-	RA-LES TES/LES user manual
		E-MAN-	<b>RA-LES-S</b> TES/LES with P/Q control user manual